

# Dance Floor Emergency

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**Count:** 32

**Wall:** 4

**Level:** Improver

**Choreographer:** Ryan Hunt (UK) - February 2025

**Intro: 16 counts (after 8 seconds)**

**Rocking Chair, Jazz Box 1/4 Cross**

**1-2 Rock R forward (1), Recover on L (2)**

**3-4 Rock R back (3), Recover on L (4)**

**5-6 Cross R over L (5), Make 1/4 R stepping back on L (6) [3:00]**

**7-8 Step R to R (7), Cross L over R (8)**

**Side, HOLD, & Side Touch, Rolling Vine**

**1-2 Step R to R (1), HOLD (2)**

**&3-4 Quickly close L next to R (&), Step R to R (3), Touch L next to R (4)**

**5-6 Make 1/4 L stepping L forward (5) [12:00], Make 1/2 L stepping R back (6) [6:00]**

**7-8 Make 1/4 L stepping L to L (7) [3:00], Touch R next to L (8) \*Restart here on Walls 3 & 9**

**Non-turning option: replace rolling vine with regular grapevine: side, behind, side, touch.**

**Dorothy Steps x2, Rock Forward, Recover, 1/4 Side, Point**

**1-2& Step R to R diagonal (1), Lock L behind R (2), Step onto R (&)**

**3-4& Step L to L diagonal (3), Lock R behind L (4), Step onto L (&)**

**5-6 Rock R forward (5), Recover on L (6)**

**7-8 Make 1/4 R stepping R to R side (7) [6:00], Point L to L side (8)**

**1/4 Forward, 1/2 Back, Coaster Step, Heel Struts w/ Shoulder Touches & Robot Arms**

**1-2 Make 1/4 L stepping L forward (1) [3:00], Make 1/2 L stepping R back (2) [9:00]**

**3&4 Step L back (3), Close R next to L (&), Step L forward (4)**

**5-6 Dig R heel forward (5), Drop R toes (6)**

**Arms: Cross arms over chest touching R hand to L shoulder & L hand to R shoulder (5),  
Touch hands to respective shoulders i.e. R hand to R shoulder & L hand to L shoulder  
(6)**

**7-8 Dig L heel forward (7), Drop L toes (8)**

**Arms: Raise R hand forward with palm facing left as left hand is down by left side (7),  
Switch L hand forward with palm facing right as right hand drops down by right side  
(8)**

**Restarts: After 16 counts on Walls 3 and 9 (both facing 9:00)**

**Ending: Drop head and look to the floor on count 32 of Wall 12 (facing 12:00), holding  
the robot pose with the L hand forward!**